Application I. Thermal pressurization of pore fluids



1 – D Fourier's heat conduction equation:

$$\frac{\partial}{\partial t}T = \chi \frac{\partial^2}{\partial \zeta^2}T + \frac{1}{c}q$$

Coupling of temperature T with pore fluid pressure p_{fluid} .

$$\frac{\partial}{\partial t} p_{fluid} = \frac{\alpha_{fluid}}{\beta_{fluid}} \frac{\partial}{\partial t} T - \frac{1}{\beta_{fluid}} \frac{\partial}{\partial t} \Phi + \omega \frac{\partial^2}{\partial \zeta^2} p_{fluid}$$

where χ is the thermal diffusivity, *c* the heat capacity for unit volume, α_{fluid} the coefficient of thermal expansion, β_{fluid} the compressibility coefficient, Φ the porosity and $\omega = k/\eta_{fluid}\beta_{fluid}\Phi$ the hydraulic diffusivity (being *k* the permeability of the medium and η_{fluid} the dynamic fluid viscosity). Analytical solutions at $\zeta = 0$ are:

$$T^{w^{f}}(\xi_{1},\xi_{3},t) = T_{0}^{f} + \frac{1}{2 cw(\xi_{1},\xi_{3})} \int_{0}^{t-\varepsilon} dt' \operatorname{erf}\left(\frac{w(\xi_{1},\xi_{3})}{2\sqrt{\chi(t-t')}}\right) \tau(\xi_{1},\xi_{3},t') v(\xi_{1},\xi_{3},t')$$

$$\begin{split} \widetilde{p}_{fluid}^{w^{f}}\left(\xi_{1},\xi_{3},t\right) &= p_{fluid_{0}}^{f} + \frac{\gamma}{2w(\xi_{1},\xi_{3})} \int_{0}^{t-\varepsilon} \mathrm{d}\,t' \left\{-\frac{\chi}{\omega-\chi} \operatorname{erf}\left(\frac{w(\xi_{1},\xi_{3})}{2\sqrt{\chi(t-t')}}\right) + \frac{\omega}{\omega-\chi} \operatorname{erf}\left(\frac{w(\xi_{1},\xi_{3})}{2\sqrt{\omega(t-t')}}\right)\right\} \\ &\left\{ \tau\left(\xi_{1},\xi_{3},t'\right) v\left(\xi_{1},\xi_{3},t'\right) - \frac{2w(\xi_{1},\xi_{3})}{\gamma} \frac{1}{\beta_{fluid}} \Phi\left(t'\right)} \frac{\partial}{\partial\,t'} \Phi\left(\xi_{1},0,\xi_{3},t'\right) \right\} \end{split}$$

Bizzarri and Cocco (2006a, 2006b, JGR)





The breakdown zone







Application II. Flash heating of micro – asperity contacts

RUINA – DIETERICH WITH FLASH HEATING

$$\begin{cases} \tau = \left[\begin{array}{c} \mu_{*} - a \ln\left(\frac{v_{*}}{v}\right) + \theta \end{array} \right] \sigma_{n}^{eff} \\ \frac{d}{dt} \theta = \begin{cases} -\frac{v}{L} \left[\theta + b \ln\left(\frac{v}{v_{*}}\right) \right] \\ -\frac{v}{L} \left[\theta + b \frac{v_{fh}}{v} \ln\left(\frac{v}{v_{*}}\right) + \left(1 - \frac{v_{fh}}{v}\right) \left(a \ln\left(\frac{v}{v_{*}}\right) + \mu_{*} - \mu_{fh}\right) \right] \\ v > v_{fh} \end{cases}$$

where
$$v_{fh} = \frac{\pi \chi}{D_{ac}} \left(c \frac{T_{weak} - T^{w^f}}{\tau_{ac}} \right)^2$$
 is

a weakening velocity above which flash heating is activated, T_{weak} is a weakening temperature, τ_{ac} is the (average) shear strength of asperity contacts and D_{ac} their (average) size.

Bizzarri (2009, GRL)





Application III. Melting of rocks and gouge



Bizzarri (2010, JGR)



$$\begin{split} \frac{\partial}{\partial t} T(\zeta, t) &= \chi \frac{\partial^2}{\partial \zeta^2} T(\zeta, t) + \frac{1}{c} q(\zeta, t) \\ q(\zeta, t) &= \begin{cases} \frac{\tau(t)v(t)}{2w} &, t > 0, |\zeta| \le w \\ 0 &, |\zeta| > w \end{cases} \\ t) &\equiv T(0, t) = T_0^f + \frac{1}{2cw} \int_0^{t-\varepsilon} dt' \operatorname{erf}\left(\frac{w}{2\sqrt{\chi(t-t')}}\right) \tau(t')v(t'), \\ \widetilde{T}(\zeta, t) &= \widetilde{\chi} \frac{\partial^2}{\partial \zeta^2} \widetilde{T}(\zeta, t) + \frac{d}{dt} w_m(t) \frac{\partial}{\partial \zeta} \widetilde{T}(\zeta, t) + \frac{1}{\breve{c}} \widetilde{q}(\zeta, t) \\ \widetilde{q}(\zeta, t) &= \frac{\widecheck{\tau}(\zeta, t) v(t) e^{-\frac{\zeta^2}{2w_m^2(t)}}}{\sqrt{2\pi}w_m(t)} \Theta(t-t_m) \\ \widetilde{T}^f(t) &\equiv \widetilde{T}(0, t) = T_m + \frac{\left(\sqrt{\frac{2\pi}{c}} + \pi \operatorname{erf}\left(\frac{1}{\sqrt{2}}\right) - \sqrt{2\pi}\right)}{2\pi \, \breve{c} \, \breve{\chi}} \\ \cdot \Theta(t-t_m)w_m(t) \, \breve{\tau}(t)v(t). \end{split}$$

Coulomb friction is no longer valid and we then consider a Newtonian fluid (e.g., Fialko, 2004):

$$\tau^{(\rm NF)} = \breve{\eta} \, \frac{\upsilon}{2 \, w_m}$$

$$\widecheck{\eta}(\zeta,t) = \widecheck{K} e^{\overbrace{T_a}{\widecheck{T}(\zeta,t-\varepsilon) + 273.15}}$$

Bizzarri (2010, JGR)

Melting enhances supershear EQs



Transition to a viscous rheology





Application IV. Mechanical Iubrication







- Many different physical and chemical mechanisms may occur during faulting
- They strongly affect the overall dynamics of the fault, the radiated energy and the resulting ground motions
- Thermal pressurization of pore fluids, flash heating, melting and mechanical lubrication tend to enhance supershear ruptures...
- ... produce a nearly complete stress drop (heat paradox)
- increase the (equivalent) slip—weakening distance and thus the "fracture" energy
- In some cases the weakening behavior becomes exponential, as suggested by laboratory observations

- Different competing mechanisms can significantly affect the recurrence time of an eartquake sequence...
- ... and they can make the concept itself of the seismic cycle meaningless

Open questions and future developments

 Theoretical results will predict a nearly complete stress drop and therefore we should find a signature of these high stress drop values in the recorded seismograms. <u>Seismological estimates of stress drop do not support</u> <u>such an evidence</u>;

the estimation of stress drop from seismic waves is biased (for instance by the difficulties in analyzing high frequency radiation)

or

the effects of pressurization, melting and so on on the dynamic traction evolution are less pronounced

2) We need to test theoretical predictions against laboratory evidence; numerical results definitively represent an input for the development of next-generation machines



Current high velocity lab. experiments only deal with friction (of pre-cut surfaces) and not with fracture (of intact rocks)



We need to reproduce real-world conditions in terms of BOTH high sliding velocity and confining stress

3) Do real data (recorded during natural earthquakes) contain signatures of the specific friction law governing the sesimogenic fault?

We know from numerical models that, for ruptures having exactly the same energetics (namely, the same fracture energy density), the resulting ground motions are virtually indistinguishable

This slide is empty intentionally.



Support Slides: Parameters, Notes, etc.

To not be displayed directly. Referenced above.

Slip - Weakening Friction Laws

$$\tau = \begin{cases} \left[\mu_u - (\mu_u - \mu_f) \frac{u}{d_0} \right] \sigma_n^{eff} & , u < d_0 \\ \mu_f \sigma_n^{eff} & , u \ge d_0 \end{cases}$$



Barenblatt (1959a, 1959b), <u>Ida</u> (<u>1972</u>), Andrews (1976a, 1976b), and many authors thereinafter

 d_0 is the characteristic slip – weakening distance



DIETERICH - RUINA WITH VARYING NORMAL STR.

$$\begin{cases} \tau = \left[\begin{array}{c} \mu_{*} - a \ln \left(\frac{v_{*}}{v} \right) + b \ln \left(\frac{\Psi v_{*}}{L} \right) \right] \sigma_{n}^{eff} \\ \frac{d}{dt} \Psi = 1 - \frac{\Psi v}{L} - \left(\frac{\alpha_{LD} \Psi}{b \sigma_{n}^{eff}} \right) \frac{d}{dt} \sigma_{n}^{eff} \end{cases}$$

Response to an abrupt jump in load

<u>Linker and Dieterich (1992)</u>, Dieterich and Linker (1992), Bizzarri and Cocco (2006a, 2006b)



Crack vs. Pulse

