Appendix A

Relations between the slip – weakening characteristic length and the breakdown zone time

In this section we derive an expression that connect the slip-weakening characteristic distance d_0 and the breakdown time T_b .

Let us consider, in the x_1t plane, an arbitrary point of the crack tip (x_1^*, t^*) ; by definition, the slip in this point is zero: $u(x_1^*, t^*) = 0$. Let us consider also the point $(x_1^*, t^* + T_b)$; by definition of breakdown time it results $u(x_1^*, t^* + T_b) = d_0$. Therefore we have:

$$\frac{u(x_1^*, t^* + T_b) - u(x_1^*, t^*)}{T_b} = \frac{d_0}{T_b}$$
(A.1)

In full of generality the breakdown time is a whole multiple of the time step:

$$T_b = n Dt$$
, $n \ge 1$

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and thus it is possible to write the first member of (A.1) as follow:

$$\frac{u(x_{1}^{*},t^{*}+T_{b})-u(x_{1}^{*},t^{*})}{n Dt} = \frac{1}{n}$$

$$\frac{u(x_{1}^{*},t^{*}+T_{b})-u(x_{1}^{*},t^{*}+T_{b}-Dt)+u(x_{1}^{*},t^{*}+T_{b}-Dt)+\dots+}{Dt}$$

$$\frac{-u(x_{1}^{*},t^{*}+T_{b}-(n-1)Dt)+u(x_{1}^{*},t^{*}+T_{b}-(n-1)Dt)-u(x_{1}^{*},t^{*})}{Dt}$$
(A.2)
$$\frac{-u(x_{1}^{*},t^{*}+T_{b}-(n-1)Dt)+u(x_{1}^{*},t^{*}+T_{b}-(n-1)Dt)-u(x_{1}^{*},t^{*})}{Dt}$$

In (A.2) we have add and subtract couples of values of displacement u in the time steps between $t^* + T_b - Dt$ and $t^* + T_b - (n-1) Dt$. In this way in (A.2) we recognize the definition of the slip velocity, and therefore we rewrite (A.2) as:

$$\frac{1}{n} \sum_{k=1}^{n} \dot{u} \Big(x_1^*, t^* + T_b - (k-1) \mathbf{D} t \Big)$$
(A.3)

Inserting (A.3) in (A.1) we have:

$$d_{0} = T_{b}\left(x_{1}^{*}\right) \underbrace{\sum_{k=1}^{n} \dot{u}\left(x_{1}^{*}, t^{*} + T_{b} - (k-1) \mathbf{D}t\right)}_{n}$$
(A.4)

In this expression we have indicated the dependence of T_b on x_1^* to emphasize the fact that the breakdown time is variable along the fault line, as we have discussed in section 4.1. If we denote with the symbol $< \ldots >_{t_b}$ the average of the slip velocity over the times t_b within the cohesive zone (where the displacement is between 0 and d_0), we can briefly rewrite the formula (A.4) for d_0 as

$$d_0 = T_b\left(x_1^*\right) \left\langle \dot{u}\left(x_1^*, t_b\right) \right\rangle_{t_b}$$
(A.5)